Development of Scheduling Coordination System for Assembly Plants of Shipbuilding

98

207-43

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Abstract

The production process of shipbuilding is very complex in nature. To build an efficient shipbuilding scheduling system so as to reduce the inherent computational complexity, DAS (Daewoo Shipbuilding Scheduling System) has adopted a two-layered hierarchical architecture. In the hierarchical architecture, individual scheduling systems composed of a higher-level dock scheduler, DAS-ERECT and lower-level assembly plant schedulers, DAS-PBS, DAS-3DS, DAS-NPS, and DAS-A7 try to search the best schedules under their own constraints.

However, as an individual scheduler does not communicate with others during scheduling an assembly plant, another similar individual scheduler can not resolve trivial problems caused by an individual scheduler. That is, even if an individual scheduler optimizes an assembly plant, it guarantees only the local optimum.

In this paper, we suggest 'Knowledge-Based Load Balancing and Load Transfer Algorithm' to resolve the problems among the multiple assembly plant schedulers. The one is a 3-dimensional look ahead load balancing before scheduling assembly plants using the domain knowledge, while the other is a 3-dimensional post load transfer after scheduling assembly plants.

A prototype scheduling coordination system, DAS-ASICS (Assembly Schedule Integrated Control System), is implemented as a subsystem of DAS using the expert system development tool UNIK on SUN SPARC station. A series of experiments using the real-world data are also carried out to guide the equilibrium of load among assembly plant schedulers.

1.

가? (dock)

(block)'

400 ~ 500

, ,

(crane) ,

' (erection)' .

, 'DAS

< 1> ' (Hierarchical Architecture)' .
, DAS-ERECT

, DAS-PBS, DAS-

3DS, DAS-NPS, DAS-A7

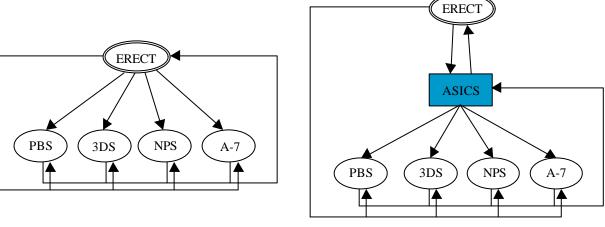
가 가

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< 2> ' (DAS-ASICS, Assembly Schedule Integrated Control System)'

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< 1> DAS < 2> DAS

2.

NP-hard 가 ,

. (Distributed

. (Distributed

Operating System) CPU

 $[1][2]. \hspace{1cm} , \hspace{1cm} (computational \ complexity) \hspace{1cm} , \hspace{1cm} (learning) \hspace{1cm} \nearrow \hspace{1cm} ,$

(dynamic rescheduling or reactive scheduling) 7, , ,

(AI-Based Approach) , DAS [3]. (Agent-Based

Supply Chain Management) ,

[4][5].

3.

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3.1.

3.1.1.

(1) , , , 1 , 2 , 3 7t . 2

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(DEFRAME Pref1099-227
        (IS-A PrefBlk)
        (Partof Pref1099)
        (Shop1 3DS)
        (Shop2 A-7)
         (Shop3)
         (DivShop\ N+3)
       (Dur1 (G 8) (H 7) (R 7) (S 4))
       (Dur2 (G 10) (H 7) (R 7) (S 5))
       (Dur3\ (G)\ (H)\ (R)\ (S))
         (DivDur (G 8) (H 4) (R 7) (S 4)))
                             <
                                    3>
(2)
          가
                                          PBS
                                                                                    , PBS
                                                    3DS
3DS
                                                                      가
            , PBS
                        NPS
                                             single hull
     (DEFRAMED PriorPBS23DS
      (IS-A Prior)
      (From PBS)
      (To 3DS)
      (Prior1 (Unit DecUnit) (ErrorR 0.1))
      (Prior2 (Proj Container Ro/Ro B/C COTorVLCC))
      (Prior3 (Blk 1 2 6 5 7 4)))
    (DEFRAMED PriorPBS2NPS
      (IS-A Prior)
      (From PBS)
      (To NPS)
      (Inclusion (Blk (B/C 1 5 6) (Container 1) (COTorVLCC 1 4)) (Weight 220)))
                           <
                                  4>
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4 24-25 .

:Session A 02.5

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. (MH = JL *

(3)

)가 . , , . .

3.1.2.

(1)

가 .

(2) (FT) (ST) 가

(3) Time slot

, , 가 .

3.2.

(1) , line ,

(IS-A SubShopMH)
(SubShop 3DS-G)
(1996/06 (capa 43637.776000) (used 49828.210865)

 $(1099\text{-}227\text{-}G7\ 220.000000)\ (1102\text{-}267\text{-}G9\ 342.571429)\ (1103\text{-}221\text{-}G7\ 128.000000))$

(1996-24 (capa 11163.152000) (used 12452.356822) (1099-227-G7 47.142857) (1102-267-G9 93.428571) (1103-221-G7 100.571429)))

(1099-22/-G/4/.14285/)(1102-26/-G9 93.4285/1)(1103-221-G/100.5/1429))) < 5>

(2)

•

3.3.

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iteration

가 . ,

. step

(delayed block)

(1)

Step 1: 1 , .

Step 2: 7,

go to step 3.

Step 3: 7 ver-capa shop under-capa shop .

Step 4: over-capa under-capa

movable block list .

Step 5: movable block list .

Step 6: .

(2)

Step 1: , .

Step 2: movalbe block list . , go to step 3.

Step 3: movable block list .

Step 4: over-capa shop under-capa shop .

Step 5: under-capa shop .

Step 6:

4. Prototype

, DAS-ASICS(Assembly Schedule Integrated Control System)

. DAS-ASICS 1994 5 1996 8

・ プト (DAS II) ・
フト UNIK SUN SPARC station

71 UNIK SUN SI AKC Station

DAS-ASICS 96 6 96 11 6 .

DAS-ASICS < 1> .

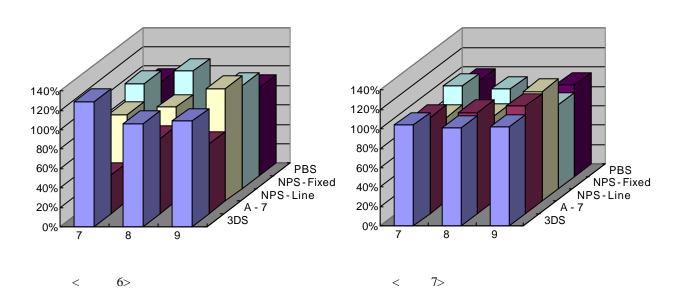
가 29.61%, 18.24%, 15.77%

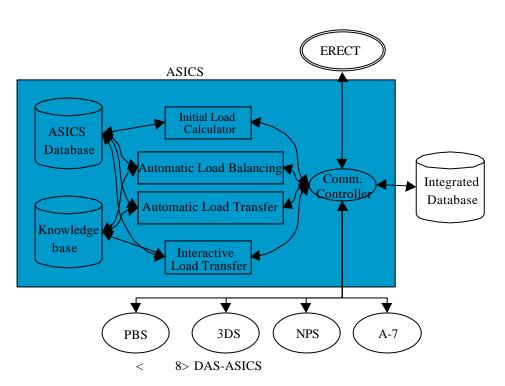
6.93%, 11.44%, 10.23%

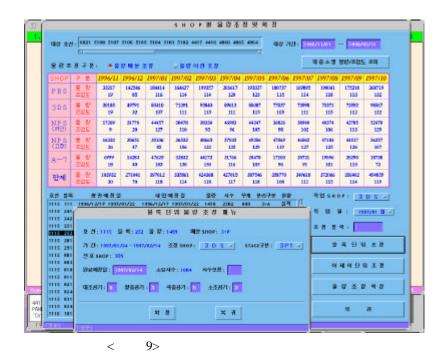
_	7	8	9
3DS	129%	106%	109%
A-7	40%	78%	72%
NPS-Line	89%	97%	116%
NPS-Fixed	108%	121%	106%
PBS	97%	71%	91%
	93%	95%	99%
	29.61%	18.24%	15.77%

7	8	9
104%	101%	102%
99%	104%	111%
86%	88%	113%
106%	103%	86%
98%	74%	94%
99%	94%	101%
6.93%	11.44%	10.23%

< 1> < 2>







5.

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, ,

. DAS-

ASICS(Assembly Schedule Integrated Control System)

DAS-ASICS

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