Development of Dual PZT Transducers for Reference-Free Crack Detection in Thin Plate Structures

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***Abstract*—A new Lamb-wave-based nondestructive testing (NDT) technique, which does not rely on previously stored baseline data, is developed for crack monitoring in plate structures. Commonly, the presence of damage is identified by comparing "current data" measured from a potentially damaged stage of a structure with "baseline data" previously obtained at the intact condition of the structure. In practice, structural defects typically take place long after collection of the baseline data, and the baseline data can be also affected by external loading, temperature variations, and changing boundary conditions. To eliminate the dependence on the baseline data comparison, the authors previously developed a reference-free NDT technique using 2 pairs of collocated lead zirconate titanate (PZT) transducers placed on both sides of a plate. This reference-free technique is further advanced in the present study by the necessity of attaching transducers only on a single surface of a structure for certain applications such as aircraft. To achieve this goal, a new design of PZT transducers called dual PZT transducers is proposed. Crack formation creates Lamb wave mode conversion due to a sudden thickness change of the structure. This crack appearance is instantly detected from the measured Lamb wave signals using the dual PZT transducers. This study also suggests a reference-free statistical approach that enables damage classification using only the currently measured data set. Numerical simulations and experiments were conducted using an aluminum plate with uniform thickness and fundamental Lamb waves modes to demonstrate the applicability of the proposed technique to reference-free crack detection.**

I. Introduction

For structural health monitoring (SHM) and nondestructive testing (NDT) of plate structures, Lamb waves have received a great deal of attention because they can propagate over considerable distances with little attenuation. Many researchers have investigated Lamb wave propagations and their applications to damage detection [1]–[10]. The conventional Lamb wave based damage detection techniques focus on schemes where the presence of damage is identified by comparing "current" data with "baseline" data measured at the intact condition of a target structure. However, significant technical challenges exist when realizing this pattern comparison for field applications. For instance, operational and environmental variations of the system such as temperature variation can produce significant changes in the measured signals, masking potential signal changes due to structural damage [11].

To overcome the drawbacks of the conventional NDT methods, a NDT technique, which does not rely on previously obtained baseline data, was proposed by the authors for crack detection [12]. In a thin uniform elastic medium such as an aluminum plate, the formation of a crack causes the propagating Lamb modes to be transformed to other modes. In this previous study, it has been shown that converted Lamb wave modes due to crack formation can be instantaneously extracted using 4 identical lead zirconate titanate (PZT) transducers placed on both sides of the specimen.

In practice, it can be challenging to align PZT transducers on both sides of plates, and the PZT placement can be limited only to a single side of the specimen. The present study was especially motivated by the necessity of attaching transducers only on a single surface of a structure for certain applications such as aircraft. In the present study, the former reference-free damage detection technique is further advanced so that mode conversion due to crack formation still can be identified using only 2 transducers placed on a single surface. For this purpose, a new PZT transducer design called dual PZT transducer is proposed.

This paper is organized as follows. First, a new concept of damage detection using dual PZT transducers is proposed. Next, a reference-free damage classifier that distinguishes signal changes due to crack from initial errors caused by PZT imperfection is proposed. Finally, experimental tests as well as numerical simulations are executed to investigate the applicability of the proposed NDT technique to crack detection.

II. Theoretical Background

A. Theoretical Framework for Crack Detection Using Dual PZT Transducers

In this study, a new design of a dual PZT transducer (hereafter, dual PZT) is conceived so that mode conver-

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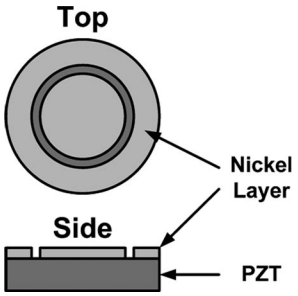


Fig. 1. A schematic drawing of a dual PZT transducer: The dual PZT transducer is fabricated from a circular PZT by etching the top nickel electrode layer into inner circular and outer ring parts.

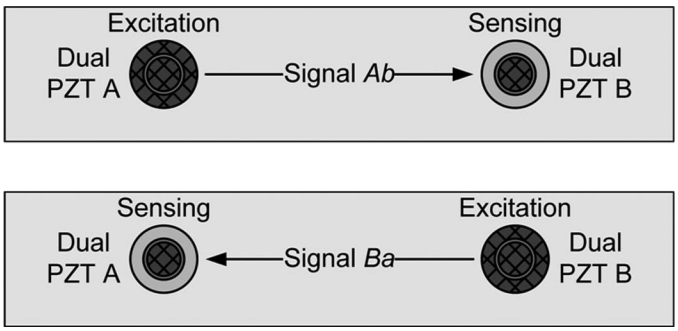


Fig. 2. A schematic diagram of two sets of guided wave signals generated and sensed using two identical dual PZT transducers: Signal *Ab* is obtained using both the ring and inner circle parts of dual PZT A (PZT *A*) as an actuator and the inner circle part of dual PZT B (PZT *b*) as a sensor. Signal *Ba* is defined in a similar manner. The patterned areas denote dual PZT parts used for excitation or sensing.

sion due to crack formation can be identified using dual PZTs placed only on a single surface. Fig. 1 illustrates the schematic drawing of a dual PZT. The dual PZT is fabricated from a circular PZT by dividing the top nickel electrode layer into inner circular and outer ring portions through an etching process.

Fig. 2 shows 2 identical dual PZTs (dual PZTs A and B) placed on the top surface of an intact plate. Signal *Ab* in Fig. 2 denotes the response signal measured at the inner circle part of dual PZT B (PZT *b*) when the excitation is applied to both the ring and inner circle parts of dual PZT A (PZT *A*). Signal *Ba* is defined in a similar manner (Fig. 2). Here, it is assumed that a narrowband toneburst signal at a specific frequency is used so that only symmetric and antisymmetric zero-order modes (S_0 and A_0 modes) are generated and measured [13].

We first show that signals *Ab* and *Ba* are identical when damage is not present. To examine this idea, the coupling coefficients of the dual PZT are introduced first. When an excitation voltage is applied to both the ring and inner circle parts (PZT *A* or PZT *B*), the coupling coefficients from the electrical energy to the strain energy are defined as K_S and K_A for the S_0 and A_0 mode, respectively. Similarly, k_S and k_A represent the coupling coefficients of each mode when the input voltage is applied only to the inner circle part (PZT *a* or PZT *b*). Note that this coupling coefficient for excitation is identical to the coefficient for sensing (the coupling coefficient from the strain energy to the electrical energy of the output voltage) [14].

When the amplitudes and shapes of the S_0 and A_0 modes in signals *Ab* and *Ba* are presented in the frequency domain, the S_0 mode in signal *Ab* can be expressed as [15], [16]:

$$k_S(\omega)\cdot m(\omega)\cdot T_S(\omega)\cdot K_S(\omega)\cdot G(\omega)\cdot I(\omega), \tag{1}$$

where $I(\omega)$ denotes a voltage input applied to the exciting PZT, and $G(\omega)$ is an electromechanical transfer function at PZT *A*. $K_S(\omega)$ represents the coupling coefficient for the S_0 mode at PZT *A*. In (1), K_S is used instead of K_S^2 as the coupling coefficient because (1) represents the amplitude and shape of the S_0 mode instead of the energy. Also, K_S is considered to be frequency dependent in (1). $T_S(\omega)$ is a structure's transfer function for the S_0 mode and reflects the shape change of the S_0 mode due to Lamb wave dispersion; $m(\omega)$ is a mechanical-electro transfer function at PZT *b*, and $k_S(\omega)$ is the coupling coefficient for the S_0 mode at PZT *b*. Hereafter, the angular frequency ω is no longer going to be explicitly shown in the equations and figures for brevity. In a similar fashion, the A_0 mode in signal *Ab* can be expressed as $k_A m T_A K_A G I$, and T_A denotes the structure's transfer function for the A_0 mode. $K_A G$ at PZT *A* and $k_A m$ at PZT *b* are the electromechanical and mechanical-electro transfer functions of the A_0 mode, respectively.

Fig. 3 illustrates the schematic diagram of signals *Ab* and *Ba* in the absence of damage. In Fig. 3, each Lamb wave mode is drawn with its frequency function. Fig. 3 is drawn based on the assumption that the S_0 mode travels faster than the A_0 mode. The arrival times of the S_0 modes in signals *Ab* and *Ba* are identical because the S_0 mode travels the same distance with the identical speed in both directions. Because the S_0 modes in both signals can be expressed identically in the frequency domain, they have the same amplitudes and shapes in the time domain. In a similar fashion, it can be shown that the A_0 modes in signals *Ab* and *Ba* are identical (Fig. 3).

Next, the effects of a crack on Lamb wave propagation are discussed. If Lamb waves propagating along a uniform thickness encounter a discontinuity such as a sudden variation in thickness, portions of the waves will be reflected at the discontinuity and the rest will be transmitted through it. When the S_0 mode arrives at a discontinuity as shown in Fig. 4, it is separated into the S_0 and A_0 modes (denoted as S_0/S_0 and A_0/S_0 modes, respectively). Similarly, the A_0 mode is divided into the S_0 and A_0 modes (S_0/A_0 and A_0/A_0 modes) [17], [18].

Fig. 5 illustrates that signals *Ab* and *Ba* are no longer identical when a crack is introduced. It is assumed in Fig. 5 that the crack is located closer to dual PZT A than to dual PZT B. In Fig. 5, the amplitude ratio of the transmitted but unconverted S_0/S_0 mode to the incident S_0 mode is denoted as α. Similarly, β denotes the amplitude ratio of the A_0/A_0 mode with respect to the incident A_0 mode. Note that the amplitude ratio of the S_0/A_0 mode

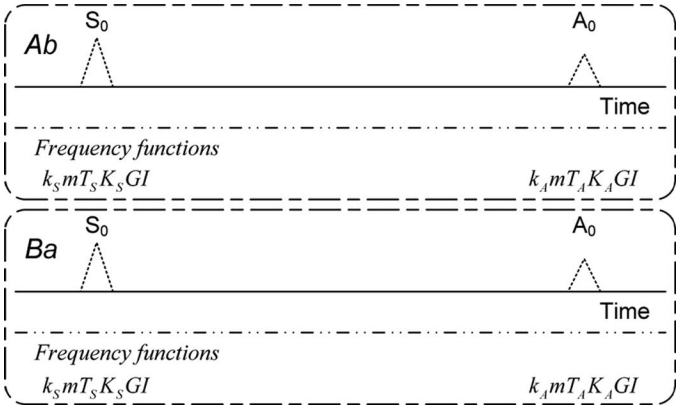


Fig. 3. Comparison between signals Ab and Ba in an intact plate: It is shown here that these two signals are identical when damage is absent. Each Lamb wave mode is drawn with its frequency function. I denotes the voltage input, and $K_S G$ and $K_A G$ are the electromechanical transfer functions at PZT A. T_S and T_A are the structure's transfer functions; $k_S m$ and $k_A m$ are the mechanical-electro transfer functions at PZT b. Subscript S and A represent the S_0 and A_0 modes, respectively.

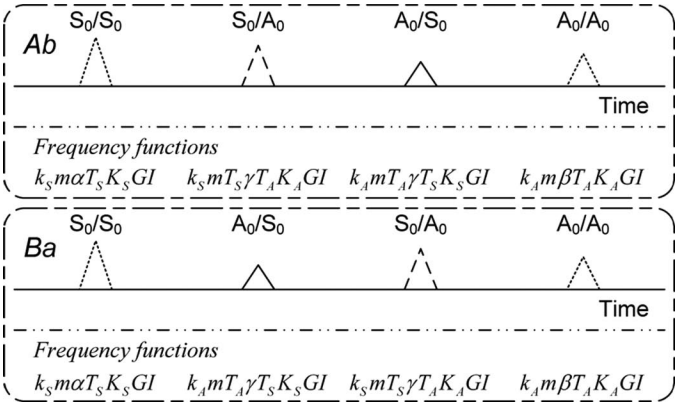


Fig. 5. Comparison between signals Ab and Ba in a damaged plate: It is shown that signals Ab and Ba are no longer identical as damage appears; α and β represent the amplitude ratio of the S_0/S_0 mode to the S_0 mode and that of the A_0/A_0 mode to the A_0 mode, respectively; γ denotes the amplitude ratio of the S_0/A_0 mode to the A_0 mode and that of the A_0/S_0 mode to the S_0 mode.

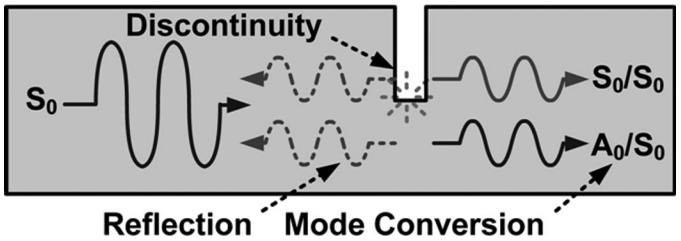


Fig. 4. Generation of mode conversion and reflection due to a discontinuity in a plate with a uniform thickness.

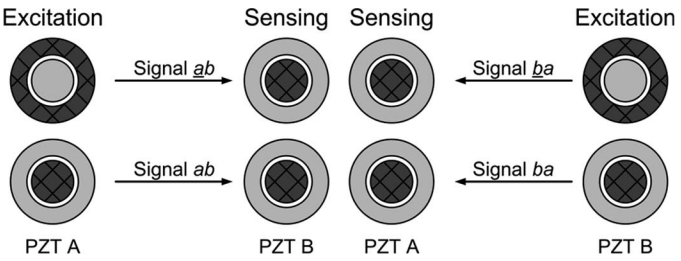


Fig. 6. The notations of various Lamb signals generated and measured using different sizes of PZTs. (Note: Only the patterned areas are activated for excitation or sensing.)

to the A_0 mode is identical to that of the A_0/S_0 mode to the S_0 mode [19]. Hereafter, this amplitude ratio is denoted as γ. To consider the shape changes of the S_0/A_0 and A_0/S_0 modes from the incident S_0 and A_0 modes, T_S and T_A are added to their frequency domain expressions, respectively.

After the crack is introduced, signals Ab and Ba contain 2 unconverted modes (S_0/S_0 and A_0/A_0 modes) and 2 converted modes (S_0/A_0 and A_0/S_0 modes). As shown in Fig. 5, the S_0/S_0 modes in signals Ab and Ba are identical because they have identical frequency functions. In a similar fashion, the A_0/A_0 modes in both signals have identical amplitudes and shapes in the time domain. As for the S_0/A_0 modes in signals Ab and Ba, it can be shown that they also have the same amplitudes and shapes. On the other hand, the S_0/A_0 mode in signal Ab and the A_0/S_0 mode in signal Ba have different amplitudes although their arrival times and shapes are identical: The frequency function of the S_0/A_0 mode in signal Ab is $k_S m T_S \gamma T_A K_A GI$ while that of the A_0/S_0 mode in signal Ba is $k_A m T_A \gamma T_S K_S GI$. In a similar manner, it can be shown that the A_0/S_0 mode in signal Ab is different from the S_0/A_0 mode in signal Ba. It should be noted that, when the same size of PZTs are used for excitation and sensing, signals Ab and Ba become always identical regardless of the presence of mode conversion ($K_S m T_S \gamma T_A K_A GI = K_A m T_A \gamma T_S K_S GI$ or $k_S m T_S \gamma T_A k_A GI = k_A m T_A \gamma T_S k_S GI$).

The novelty of the proposed study lies in using different parts of PZTs for Lamb wave generation and sensing. As a result, the presence of mode conversion can be identified simply by examining the difference between signal Ab and signal Ba. Furthermore, the findings provided here can be generalized even when additional higher symmetric and antisymmetric modes exist, although only S_0 and A_0 modes are considered in this study.

The previous findings between signals Ab and Ba can be extended to other signals pairs shown in Fig. 6. Fig. 6 illustrates the notations of various Lamb signals generated and measured using different parts of dual PZTs. In signal $\underline{a}b$, the outer ring part of PZT A ($\underline{a}$) is excited and the inner circle part of PZT B is (b) used for measurement. Signal ab is obtained by exciting the inner circle part of PZT A (a) and measuring a response from the inner circle part of PZT B (b). Signals $\underline{b}a$ and ba are defined in similar manners. As described previously, signals $\underline{a}b$ differs from signal $\underline{b}a$ when the damage is present because different parts of dual PZTs are used for excitation and sensing. In contrast, signals ab and ba are always identical regardless of damage. (The S_0/A_0 mode in signal ab matches the A_0/S_0 mode exactly in signal ba because the same parts

of the dual PZTs are used for actuation and sensing.) As a result, signal *ab* contains 2 converted modes that have identical amplitudes and shapes.

Note that Achenbach *et al.* used a similar concept for sensor-self calibration [20]. Also, a similar design of PZT transducers has been developed by Kessler and Shim [21]. They built a self-sensing unit by combining circular and ring type PZT transducers into a single unit. In their transducer unit, the inner circular PZT is exclusively designated for sensing and the ring type PZT is used only for actuation. Furthermore, it operates in a pulse-echo mode. On the other hand, the proposed dual PZT approach allows using varying sizes of PZTs for guided wave generation and measurements, and it operates in a pitch-catch mode.

Because the proposed approach relies on comparison of 2 currently obtained signals rather than comparison with any reference data, this approach is expected to reduce false alarms of defect due to changing operational and environmental conditions such as temperature.

B. Damage Classification Using Currently Measured Lamb Wave Signals

Here, a new damage classifier is developed to differentiate additional modes caused by damage from the initial errors. In the previous subsection, it is shown that signals *Ab* and *Ba* are indistinguishable when no damage is present. This is based on the assumptions that the 2 dual PZTs are identical and perfectly bonded to the host structure. In practice, these assumptions cannot be fully satisfied because of variations in dual PZT sizes and bonding conditions. This imperfection in the dual PZTs may produce differences between signals *Ab* and *Ba* and lead to positive false alarms in the absence of damage. Hereafter, the signal differences resulting from PZT imperfection are referred to as initial errors.

This damage classification scheme is based on the premise that additional modes produced by a defect have unique patterns compared with the initial errors due to PZT imperfection. The proposed technique takes advantage of not only signals *Ab* and *Ba* but also signals $\underline{a}b$ and $\underline{b}a$ for damage classification. The uniqueness of the proposed damage classifier is that damage identification is accomplished using only currently measured signals without relying on pre-stored baseline data or previously established threshold values.

In Fig. 7, the relationship among the Lamb wave signals excited using different parts of dual PZTs is shown. (Note that only different sizes of PZTs are used for excitation, and the same size of the PZT is used for sensing.) In theory, the summation of signals $\underline{a}b$ and *ab* should be identical to signal *Ab* for linear elastic waves regardless of crack presence (Fig. 7). In Fig. 8, the relative amplitude and phase information among the Lamb wave signals obtained from the different exciting PZT combinations in Fig. 6 are schematically shown. The Lamb wave signals in Fig. 8 are drawn assuming that there is a crack between

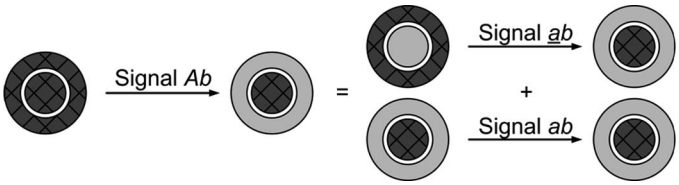


Fig. 7. The relationship among the Lamb wave signals excited using different parts of the dual PZTs.

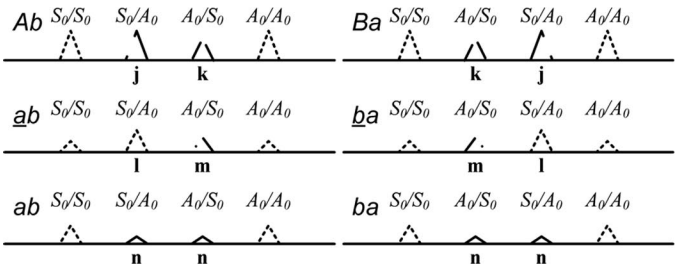


Fig. 8. A schematic diagram of Lamb wave signals excited using different portions of the dual PZT shown in Fig. 2 and Fig. 6. Note: **j**: S_0/A_0 in signal *Ab* and A_0/S_0 in signal *Ba*; **k**: A_0/S_0 in signal *Ab* and S_0/A_0 in signal *Ba*; **l**: S_0/A_0 in signal $\underline{a}b$ and A_0/S_0 in signal $\underline{b}a$; **m**: A_0/S_0 in signal $\underline{a}b$ and S_0/A_0 in signal $\underline{b}a$; and **n**: S_0/A_0 and A_0/S_0 in signals *ab* and *ba*.

dual PZTs A and B, and it is closer to dual PZT A. The additional modes produced by the crack are denoted as **j**, **k**, **l**, **m**, and **n**. For example, **j** corresponds to the S_0/A_0 mode in signal *Ab* and **k** represents the A_0/S_0 mode in signal *Ba*.

As described in the previous subsection, the S_0/A_0 and A_0/S_0 modes in signal *ab* are identical in terms of the shape and amplitude. Because the summation of signals $\underline{a}b$ and *ab* should be identical to signal *Ab*, the S_0/A_0 mode in signal *Ab* equals the summation of the corresponding modes in signals $\underline{a}b$ and *ab* ($\mathbf{j} = \mathbf{l} + \mathbf{n}$). Similarly, the A_0/S_0 mode in signal *Ab* is equal to the summation of the A_0/S_0 mode in signal $\underline{a}b$ and the A_0/S_0 mode in signal *ab* ($\mathbf{k} = \mathbf{m} + \mathbf{n}$). In Fig. 9, it is shown that "signal *Ab*–signal *Ba*" (hereafter, signal ΔAb) is identical to "signal $\underline{a}b$–signal $\underline{b}a$" (hereafter, signal $\Delta\underline{a}b$) because "$\mathbf{j} - \mathbf{l}$" equals "$\mathbf{k} - \mathbf{m}$." Furthermore, the 2 converted modes in signals ΔAb and $\Delta\underline{a}b$ are symmetric with respect to the middle time point between the arrival times of the S_0 and A_0 modes.

Based on these observations, a reference-free damage classifier is developed. First, signals ΔAb are divided into Window 1 (W_1) and Window 2 (W_2) as shown in Fig. 9. W_1 starts from the arrival time of the S_0 peak and W_2 ends at the arrival time of the A_0 peak (Fig. 9). The boundary between the 2 time windows is placed in the middle of the S_0 and A_0 peak arrival times. Signal $\Delta\underline{a}b$ is divided into Window 3 (W_3) and Window 4 (W_4) in a similar fashion (Fig. 9). By subtracting the signal in W_3 from the corresponding signal in W_1 (ΔW_{13}), the converted mode is removed while the initial errors to PZT imperfection remains. Similarly, "$W_2 - W_4$" (ΔW_{24}) contains only the initial errors.

Next, a damage index (DI) is introduced to measure the closeness between 2 arbitrary signals.

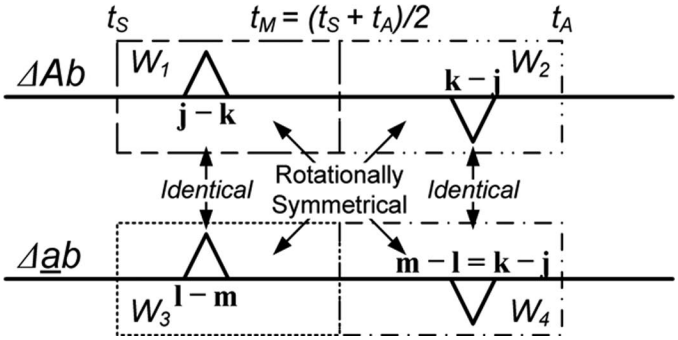


Fig. 9. A schematic diagram of measured signals ΔAb (= signal Ab – signal Ba) and $\Delta \underline{a}b$ (= signal $\underline{a}b$ – signal $\underline{b}a$): Signals in W_1 are identical to those in W_3 and rotationally symmetrical to the signals in W_2 in the presence of damage; t_S and t_A denote the arrival times of the S_0 and A_0 modes, respectively.

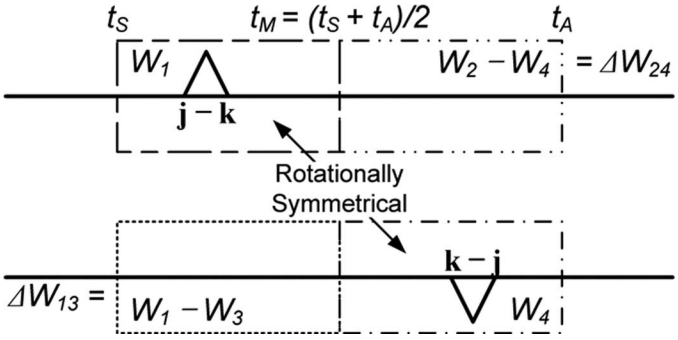


Fig. 10. A schematic diagram of W_1, ΔW_{24}, ΔW_{13}, and W_4 used to compute the first set of DIs: This first set of DIs is composed of six DIs obtained by comparing all signals in W_1, ΔW_{24}, ΔW_{13}, and W_4 and DI is defined in Table I.

TABLE I. COMBINATION I: SIX DIS OBTAINED FROM W_1, ΔW_{24}, ΔW_{13}, AND W_4.

	Damage Index between
$DI_{1,\Delta 24}$	W_1 and "$W_2{}^T - W_4{}^T$" ($\Delta W_{24}{}^T$)
$DI_{1,\Delta 13}$	W_1 and "$W_1 - W_3$" (ΔW_{13})
$DI_{1,4}$	W_1 and $W_4{}^T$
$DI_{\Delta 24,\Delta 13}$	$\Delta W_{24}{}^T$ and ΔW_{13}
$DI_{\Delta 24,4}$	$\Delta W_{24}{}^T$ and $W_4{}^T$
$DI_{\Delta 13,4}$	ΔW_{13} and $W_4{}^T$

If $DI_{1,4}$ is maximum, damage is present.
Superscript T means that the signal is reversed in the time domain before computing DI.

$$DI = \underbrace{\frac{\sqrt{\left(\sum XY\right)^2}}{\sqrt{\sum X^2 \sum Y^2}}}_{\text{Shape differences}} \times \underbrace{\frac{\min\left(\sqrt{\sum X^2}, \sqrt{\sum Y^2}\right)}{\max\left(\sqrt{\sum X^2}, \sqrt{\sum Y^2}\right)}}_{\text{Amplitude ratio between two signals}}, \quad (2)$$

where X and Y denote 2 signals being compared. Note that the first term of DI captures only the shape difference between the 2 signals while the second term examines their amplitude difference. DI becomes 1 when the shapes and amplitudes of the 2 signals are identical. As the amplitude and/or shape differences between the 2 signals increase, DI approaches 0. Note that this DI is independent of the signs of the signals. For instance, even if $X = -Y$, DI still becomes 1.

In Fig. 10, W_1, ΔW_{24}, ΔW_{13}, and W_4 are shown. By comparing all signals in these 4 windows, a total of 6 DIs are computed as shown in Table I. Among these 4 windows, only W_1 and W_4 contain converted modes when damage is present (Fig. 10). After reversing W_4 in the time domain ($W_4{}^T$), it can be shown that W_1 and $W_4{}^T$ are fully out of phase (Fig. 10). Therefore, it is expected that DI between W_1 and $W_4{}^T$ ($DI_{1,4}$) become the largest value along all 6 DIs when the damage is present. In Table I, superscript "T" represents that the signal is reversed in the time domain. Alternatively, another set of 6 DIs are conceived and presented. (Fig. 11 and Table II). In Combination II, signals in ΔW_{13}, W_2, W_3, and ΔW_{24} are used,

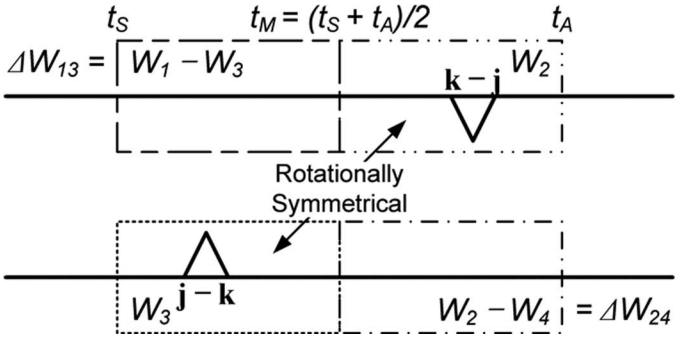


Fig. 11. A schematic diagram of ΔW_{13}, W_2, W_3, and ΔW_{24} used to compute the second set of DIs: This second set of DIs is composed of six DIs obtained by comparing all signals in ΔW_{13}, W_2, W_3, and ΔW_{24} and DI is defined in Table II.

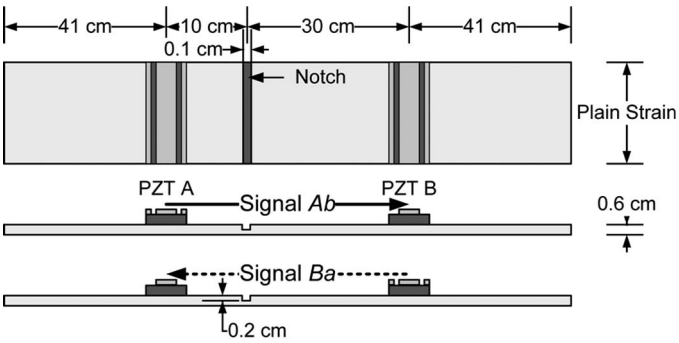
TABLE II. COMBINATION II: SIX DIS OBTAINED FROM ΔW_{13}, W_2, W_3, AND ΔW_{24}.

	Damage Index between
$DI_{\Delta 13,2}$	ΔW_{13} and $W_2{}^T$
$DI_{\Delta 13,3}$	ΔW_{13} and W_3
$DI_{\Delta 13,\Delta 24}$	ΔW_{13} and $\Delta W_{24}{}^T$
$DI_{2,3}$	$W_2{}^T$ and W_3
$DI_{2,\Delta 24}$	$W_2{}^T$ and $\Delta W_{24}{}^T$
$DI_{3,\Delta 24}$	W_3 and $\Delta W_{24}{}^T$

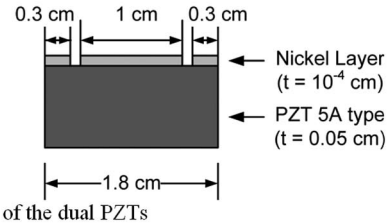
If $DI_{2,3}$ is maximum, damage is present.
Superscript T means that the signal is reversed in the time domain before computing DI.

and DI between $W_2{}^T$ and W_3 ($DI_{2,3}$) should become the maximum value when the damage is present.

Note again that no baseline data are required during this damage classification procedure because damage is identified only using currently measured Lamb wave signals. The proposed damage classifier indicates additional modes caused by damage even in the presence of the initial errors. The applicability of the proposed classification technique is numerically and experimentally validated in the subsequent sections.



(a) Dimensions of the aluminum plate



(b) Dimensions of the dual PZTs

Fig. 12. Dimensions of the aluminum plate and the dual PZTs used in the numerical simulation.

III. Numerical Simulation

The concept of using dual PZTs for crack detection was first validated through numerical simulation. COMSOL 3.4 Multiphysics software (www.comsol.com) was used for the simulation, and Lamb wave propagation in a 2-D aluminum plate was simulated using the combination of plain strain, piezo plain strain, and electrostatics modules in COMSOL software. The length of the plate was 122 cm, and its thickness was 0.6 cm. Two identical dual PZTs were attached to the plate model as shown in Fig. 12. Due to the plain strain assumption of the model, 2-D dual PZTs were also modeled with infinite width as shown in Fig. 12(a). Each PZT patch was divided into outer and inner parts as shown in Fig. 12 (b), and PZT 5A type was used for the numerical study. The thickness of the nickel electrodes and the dual PZT were 10^{-4} cm and 0.05 cm, respectively. The parameter values used in the numerical simulation are listed in Table III. A narrowband toneburst signal at 150 kHz was used as an input signal. In this study, the driving frequency was selected so that only S_0 and A_0 modes could be generated. In the simulation, Rayleigh damping coefficients were set to 10^{-4} for a mass damping coefficient and 0 for a stiffness damping coefficient, respectively. The simulation results were obtained using a time-dependent solver, and a time step was set to 0.25 μs, which is equivalent to 4 MS/sec. To control the error in each integration step, relative and absolute tolerances for the solution were chosen to be 10^{-6} and 10^{-11}, respectively. The maximum backward differentiation formula (BDF) order used for setting the degree of the interpolating polynomials in the time-stepping method was set to order 2. Finally, the model was meshed using a mapped mesh option, and the maximum size of each mesh was limited to 1 mm × 1 mm [22].

TABLE III. Parameters Used in Numerical Simulation.

Exciting frequency	150 kHz
α (Mass damping coefficient)	10^{-4}
β (Stiffness damping coefficient)	0
Sampling rate	4 MS/s
Relative tolerance	10^{-6}
Absolute tolerance	10^{-11}
Maximum BDF order	2
Mesh size (mapped mesh)	1 mm × 1 mm max.

BDF = backward differentiation formula.

Fig. 13 shows 3 pairs of signals, signals *ab* and *ba,* signals $\underline{a}b$ and $\underline{b}a$, and signals *Ab* and *Ba*, obtained from the intact condition of the plate. Each pair of signals was practically identical to each other, and it corresponded well to the theoretical expectation. The comparison among signals *ab*, $\underline{a}b$, and *Ab* in Fig. 13 indicated that the amplitudes of the S_0 and A_0 modes depended on the size of the existing PZT. For instance, both the S_0 and A_0 modes appeared in signals *ab* and $\underline{a}b$ while the S_0 mode was predominant in signal *Ab*.

Next, a notch that was 0.2-cm deep and 0.1-cm wide was introduced 10 cm away from PZT A toward PZT B. Even in the presence of the notch, signals *ab* and *ba* remained identical as shown in Fig. 14(a). However, signal $\underline{a}b$ became different from signal $\underline{b}a$ as a result of the mode conversion induced by the notch; see Fig. 14(b). Similarly, the differences between signals *Ab* and *Ba* became apparent when the damage was present; see Fig. 14(c).

As described in the previous subsection, signal $\Delta\underline{a}b$ always should be identical to signal ΔAb. This relationship between signals $\Delta\underline{a}b$ and ΔAb was demonstrated in Fig. 15. In the absence of damage, the amplitudes of both signals $\Delta\underline{a}b$ and ΔAb were zeros; see Fig. 15(a). On the other hand, converted modes, which are almost identical for signals $\Delta\underline{a}b$ and ΔAb, appeared in the presence of damage; see Fig. 15(b). The small discrepancy between 2 signals in Fig. 15(b) is attributed to errors in numerical calculation.

The numerical example presented in this subsection demonstrates the fact that a crack can be identified without relying on previously stored baseline data. The finding in the numerical simulation is further substantiated in the following experimental study.

IV. Experimental Results

A. Description of Experimental Setup

To further examine the proposed reference-free NDT technique, experimental tests have been conducted on an aluminum plate. The overall test configuration and the test specimen are shown in Fig. 16. The data acquisition system was composed of an arbitrary waveform generator (AWG), a high-speed signal digitizer (DIG), a low noise preamplifier (LNP) and a multiplexer (Fig. 16). The dimension of the plate was 122 cm × 122 cm × 0.6 cm, and

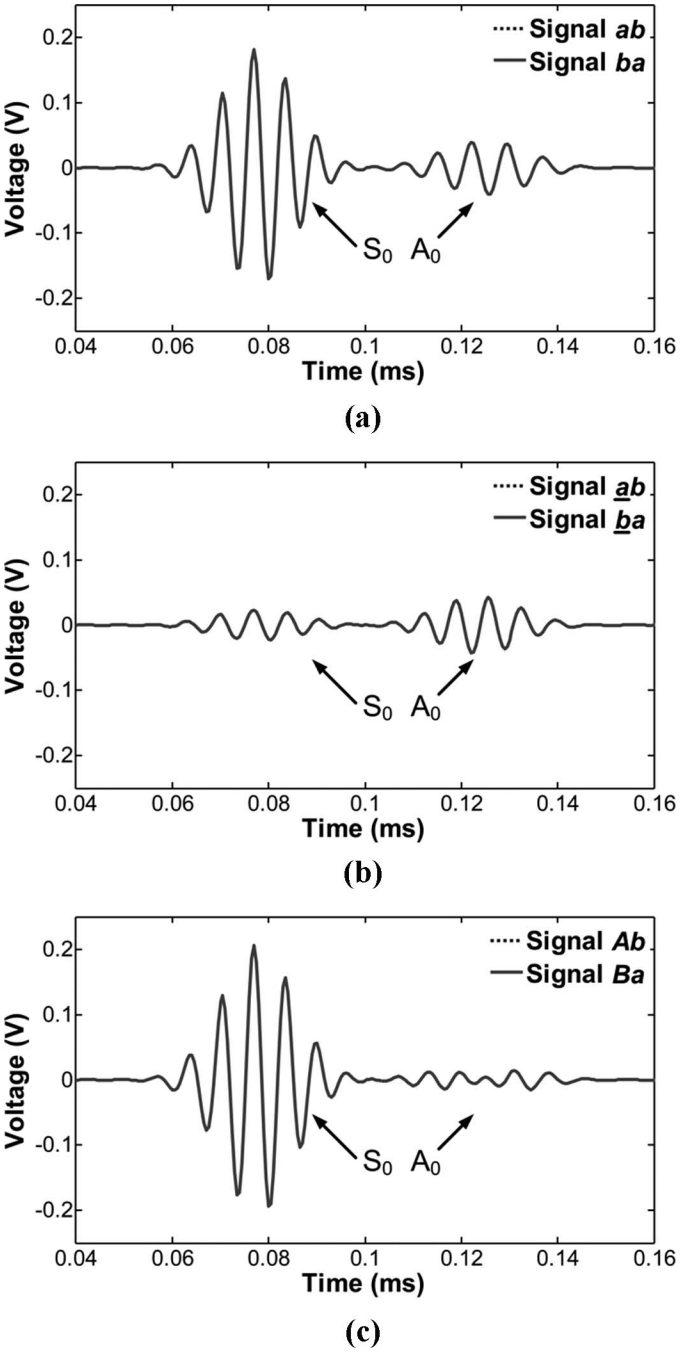


Fig. 13. Three pairs of signals—(a) signals *ab* and *ba,* (b) signals $\underline{a}b$ and $\underline{b}a$, and (c) signals *Ab* and *Ba*—simulated from the intact condition of the plate: Each pair of signals was practically identical to the other.

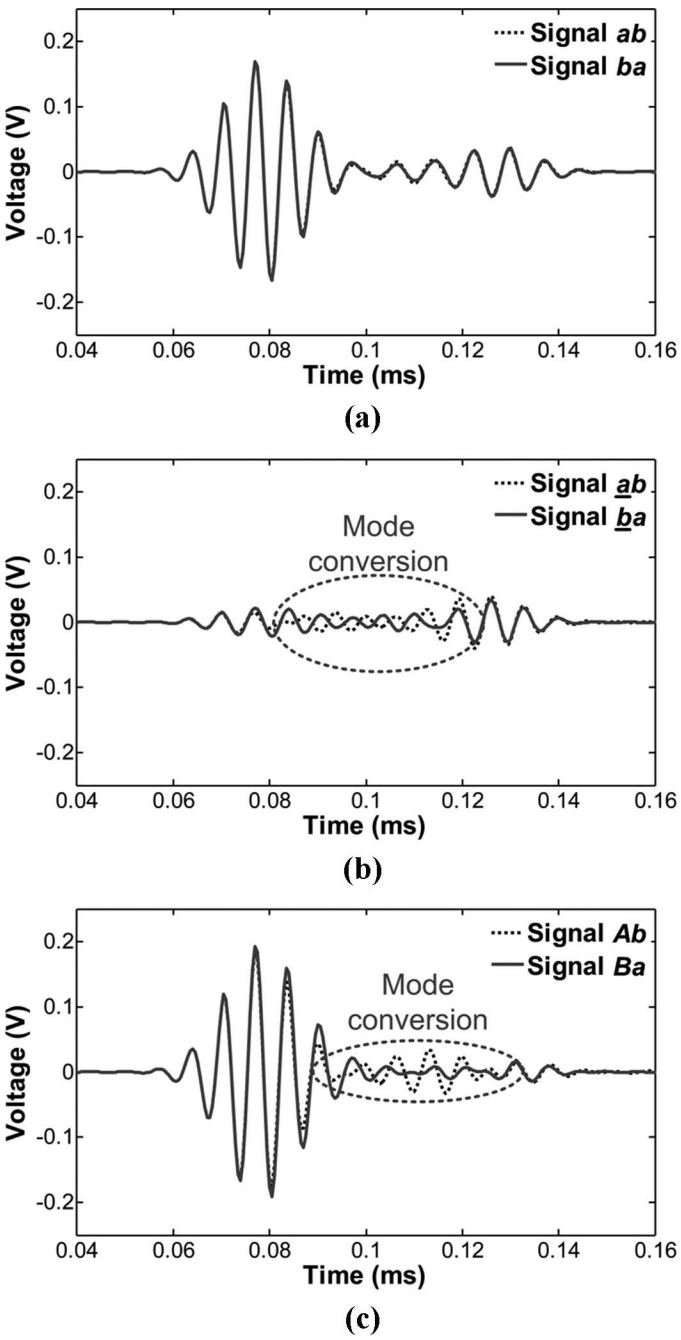


Fig. 14. Three pairs of signals—(a) signals *ab* and *ba,* (b) signals $\underline{a}b$ and $\underline{b}a$, and(c) signals *Ab* and *Ba*—simulated with a 2-mm notch: Signals $\underline{a}b$ and $\underline{b}a$ (or signals *Ab* and *Ba*) are no longer identical.

2 circular dual PZTs were mounted in the middle of the plate. PZTs A and B were 40 cm apart each other and attached to the top surface of the plate with commercial cyanoacrylate adhesive. The dual PZT transducer was fabricated by etching the top nickel electrode layer of a PSI-5A4E type PZT wafer transducer into outer and inner parts (diameter of the inner circle: 1.0 cm, diameter of the outer ring: 1.8 cm, and thickness: 0.05 cm) as shown in Fig. 17.

Using the 14-bit AWG, a toneburst signal with a 10 peak-to-peak voltage and a driving frequency of 150 kHz was generated and applied. First, both ring and inner circle parts of dual PZT A were excited by this input waveform. Then, dual PZT A generated elastic waves and the response was measured at the inner circle part of dual PZT B (signal *Ab*). When the waves arrived at dual PZT B, the voltage output from dual PZT B was amplified by the LNP with a gain of 10 and measured by the DIG. The sampling rate and resolution of the DIG were 20 MS/sec and 16 bits, respectively. To improve the signal-to-noise ratio, the response signals were measured 20 times and averaged in the time domain. After signal *Ab* was measured,

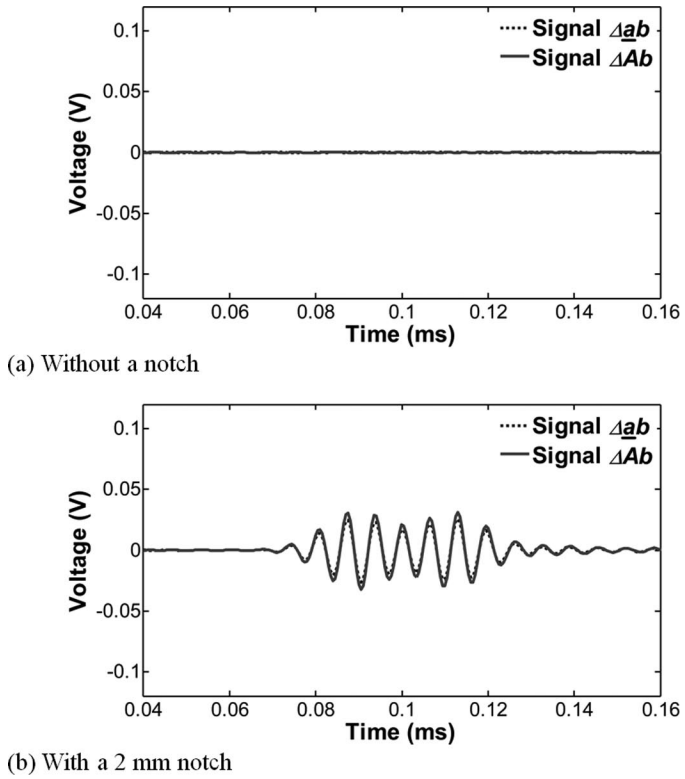


Fig. 15. Comparison of signals $\Delta \underline{a}b$ and ΔAb obtained from the undamaged and damaged conditions (numerical simulation).

the same procedure was repeated for signals Ba, ab, ba, $\underline{a}b$, and $\underline{b}a$, respectively. Detailed test results are described in the following subsection.

B. Test Results

In Fig. 18, the Lamb wave signals experimentally measured from the intact condition of the specimen are shown. As expected, signals ab and ba were practically identical; see Figs. 18(a) and (b). Signals $\underline{a}b$ and $\underline{b}a$ in Fig. 18(c) as well as signals Ab and Ba in Fig. 18(e) showed small differences even in the absence of damage due to variations in the dual PZTs' size and bonding condition; see Figs. 18(d) and (f).

Next, a 0.15-cm-deep × 0.1-cm-wide × 6-cm-long notch was introduced between dual PZTs A and B. The notch was located 10 cm away from PZT A toward PZT B. As a result, 2 additional modes due to mode conversion appeared between the existing S_0 and A_0 modes as shown in Figs. 19(c), (d), (e), and (f), while few differences were found between signals ab and ba in Figs. 19(a) and (b).

The test results indicate that mode conversion due to crack can be identified from currently measured Lamb wave signals. In the next subsection, the proposed damage classifier is tested to determine if the identified mode conversion is large enough to indicate an actual defect.

C. Reference-Free Damage Diagnosis

In Fig. 20, signals $\Delta \underline{a}b$ and signals ΔAb obtained from both damaged and undamaged conditions are shown. In

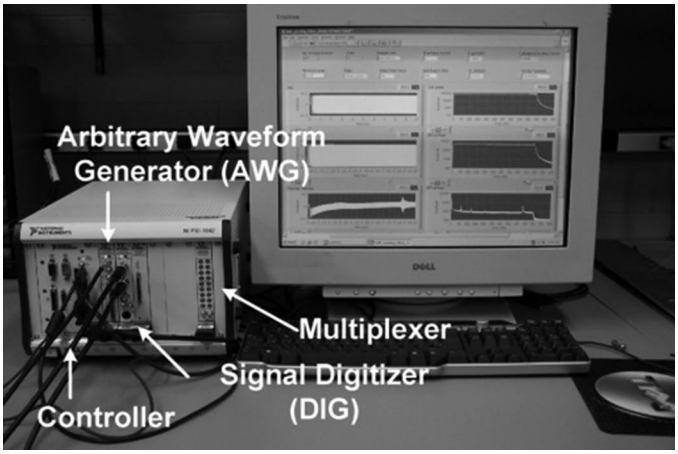


Fig. 16. Test configuration used for validation of the proposed damage detection technique.

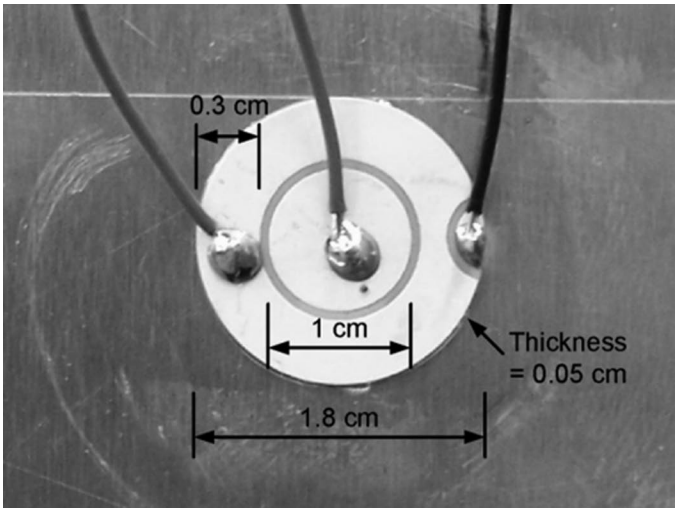


Fig. 17. The dimension of the dual PZT transducer used in this study.

theory, signals $\Delta \underline{a}b$ and ΔAb in Fig. 20(a) were supposed to be null signals. In practice, signals $\Delta \underline{a}b$ as well as signals ΔAb had some initial errors due to PZT imperfection. Because the sensors have been placed by human operation, different bonding conditions in sensors were unavoidable. As a result, large error signals appear even in the absence of damage.

After the notch was formed, mode conversion was observed in Fig. 20(b). Note that signal difference due to mode conversion was on the same order of the difference without damage. This is because the depth of the formed notch was one quarter of the thickness of the tested aluminum plate. If the depth of the notch is increased, the signal due to mode conversion would have much higher amplitude than the error signal. It also should be noted that signals $\Delta \underline{a}b$ and ΔAb are identical for both the undamaged and damaged conditions.

W_1, ΔW_{24}, ΔW_{13}, and W_4 were obtained from signals $\Delta \underline{a}b$ and ΔAb according to Combination I described in Table I and Fig. 21, and DIs were calculated using (2). In Fig. 22, 6 DIs obtained according to Combination I

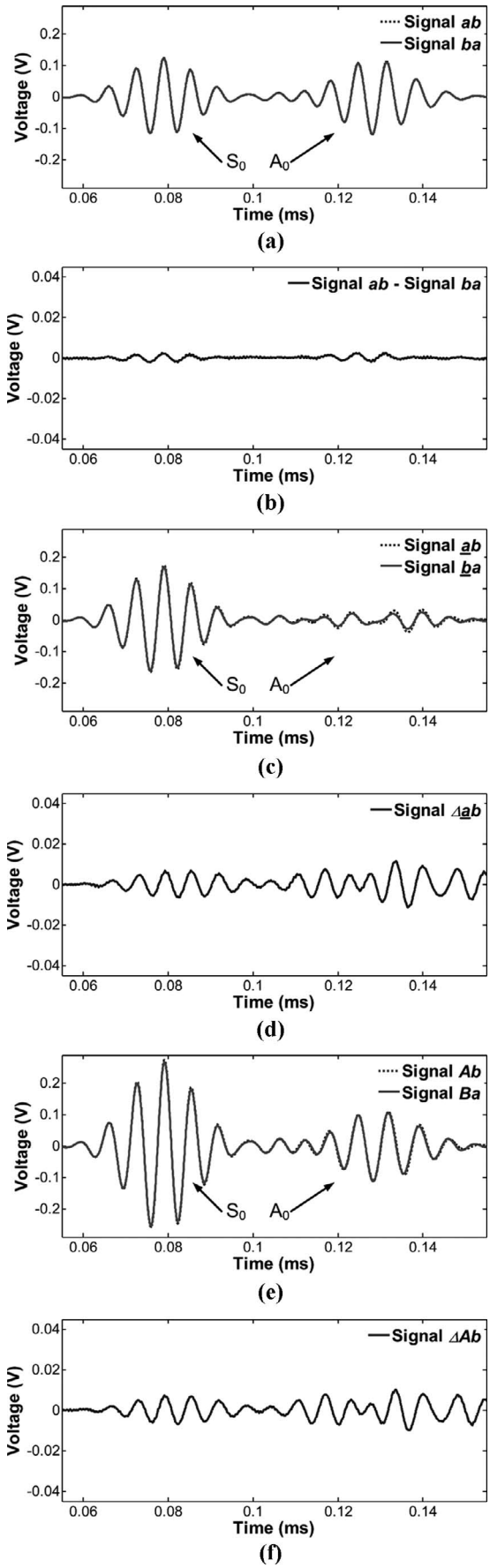


Fig. 18. Measured Lamb wave signals without a notch: (a) signals ab and ba, (b) signal ab – signal ba, (c) signals $\underline{a}b$ and $\underline{b}a$, (d) signal $\Delta\underline{a}b$, (e) signals Ab and Ba, and (f) signal ΔAb.

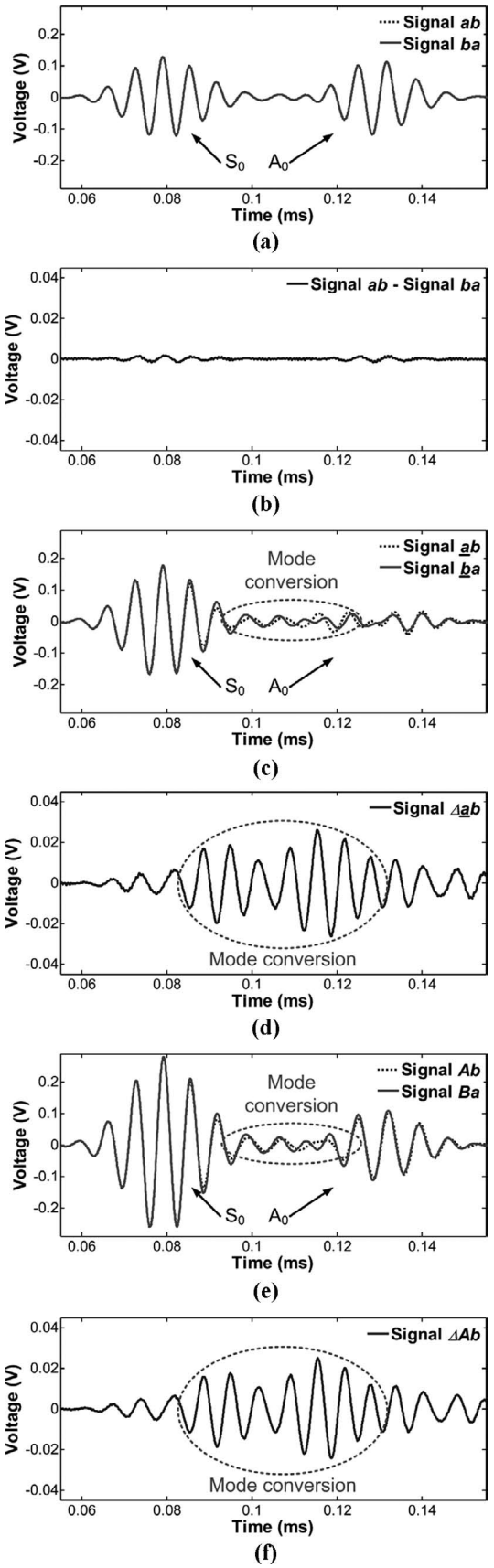


Fig. 19. Measured Lamb wave signals with a 1.5-mm notch: (a) signals ab and ba; (b) signal ab – signal ba; (c) signals $\underline{a}b$ and $\underline{b}a$, mode conversion was found between the S_0 and A_0 modes; (d) signal $\Delta\underline{a}b$; (e) signals Ab and Ba, mode conversion was found between the S_0 and A_0 modes; and (f) signal ΔAb.

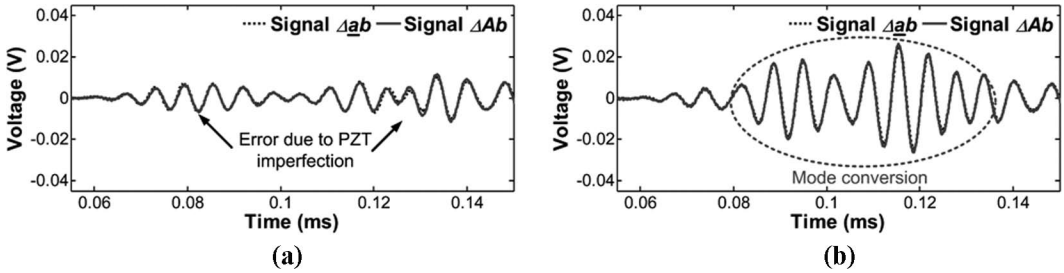


Fig. 20. Comparison of signals $\Delta \underline{a}b$ and ΔAb obtained from (a) undamaged and (b) damaged conditions. Damaged condition has a 1.5-mm-deep notch.

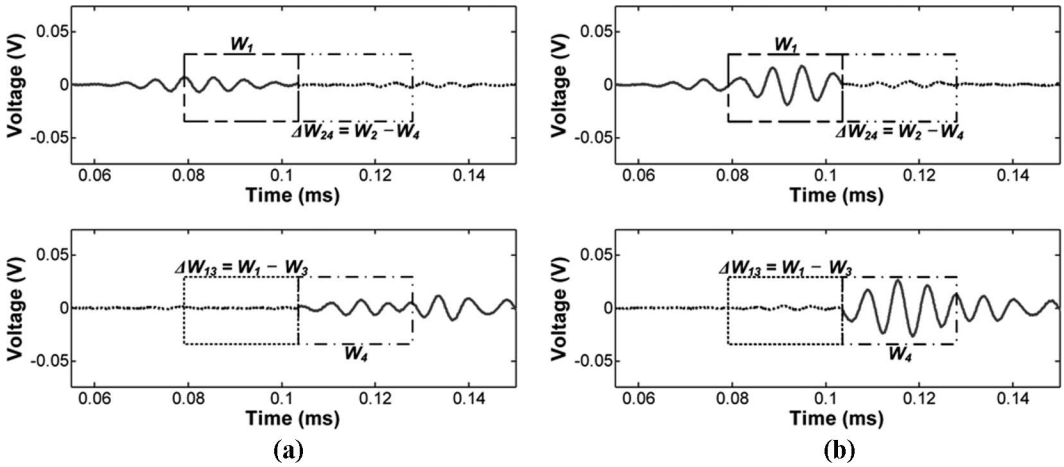


Fig. 21. W_1, ΔW_{24}, ΔW_{13}, and W_4 obtained from signals ΔAb and $\Delta \underline{a}b$ according to Combination I described in Table I and Fig. 10: (a) undamaged condition and (b) damaged condition with a 1.5-mm-deep notch.

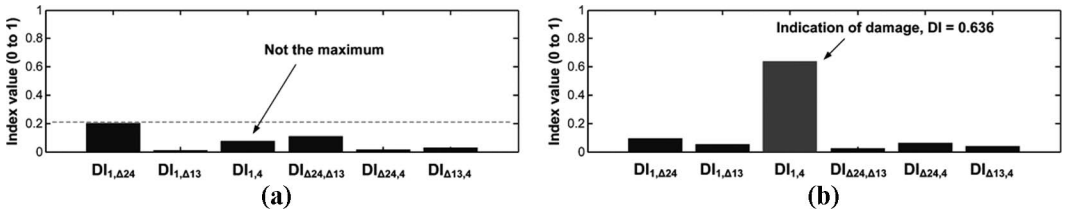


Fig. 22. Reference-free damage classification using DIs obtained according to Combination I shown in Table I (if crack damage existed, the $DI_{1,4}$ should be the maximum): (a) undamaged condition and (b) damaged condition with a 1.5-mm-deep notch.

are shown for the undamaged and damaged conditions of the plate. In the absence of damage, $DI_{1,4}$ was not the maximum among the computed DI values. The maximum DI value of 0.203 was found in $DI_{1,\Delta 24}$. After the 1.5 mm-deep notch was introduced, $DI_{1,4}$ became the maximum ($DI_{1,4} = 0.636$). Alternative DIs were calculated based on Combination II and shown in Fig. 23. Without damage, the maximum value, 0.198, was found in $DI_{3,\Delta 24}$. With the notch, $DI_{2,3}$ became the maximum value ($DI_{2,3} = 0.718$) while the second highest was $DI_{3,\Delta 24}$ (0.084).

Note that conventional techniques require comparison with baseline data to detect a crack or a notch, and their performance may deteriorate under changing operational and environmental conditions. Because the proposed method can perform damage diagnosis without direct comparison with the baseline data, it can complement the conventional techniques.

D. Damage Localization

After the presence of the damage was determined, its possible locations were estimated by measuring the arrival time of the converted mode in W_1. Signal ΔAb contains 2 converted modes, S_0/A_0 and A_0/S_0, and their arrival times depend on the location of the damage. If the damage is closer to dual PZT A, the S_0/A_0 mode arrives before the A_0/S_0 mode. If the damage is closer to dual PZT B, the A_0/S_0 mode arrives sooner. However, it cannot be determined whether the crack is closer to dual PZT A or dual PZT B based only on signals $\Delta \underline{a}b$ and ΔAb. Therefore, 2 possible damage locations are identified by assuming that the converted mode in W_1 is either the S_0/A_0 mode or the A_0/S_0 mode.

Based on the arrival times of the S_0 and A_0 modes in Fig. 20(a), the group velocities of the S_0 (V_S) and A_0 modes

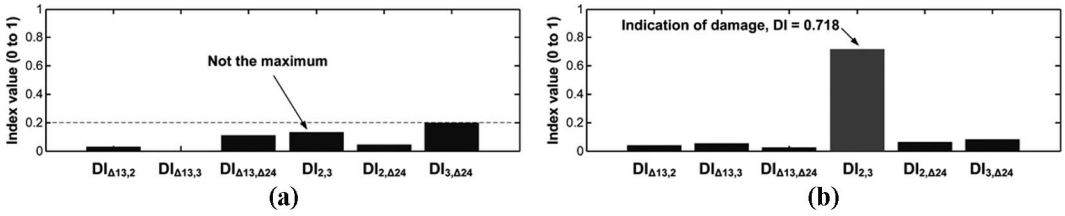


Fig. 23. Reference-free damage classification using DIs obtained according to Combination II shown in Table II (if crack damage existed, the $DI_{1,4}$ should be the maximum): (a) undamaged condition and (b) damaged condition with a 1.5-mm-deep notch.

(V_A) were estimated to be 5.063 m/ms and 3.123 m/ms, respectively. They were close to theoretical group velocities, $V_S = 5.088$ m/ms and $V_A = 3.055$ m/ms, estimated from the material property. First, one possible damage location was estimated by assuming that the converted mode in W_1 was the S_0/A_0 mode:

$$\text{The arrival time of the converted mode in } W_1 = s/V_A + \Big(\text{Distance between PZT A and PZT B } - \ s\Big)/V_S, \tag{3}$$

where s denotes the distance of the notch from dual PZT A. From the arrival time of the converted mode (0.0918 ms) and (3), s was estimated to be 10.43 cm. This estimated distance was close to the actual distance (10 cm from dual PZT A, 4.3% error). Another possible damage location was also found by assuming that the converted mode was the A_0/S_0 mode (9.91 cm from dual PZT B toward dual PZT A).

V. Conclusion

In our previous work, an NDT method was proposed so that crack damage in a thin plate structure could be detected without referencing previously stored baseline data. Using 4 identical PZT transducers placed on both sides of the specimen, mode conversion due to damage was clearly extracted. However, attaching the PZT transducers on both sides of the specimen could be a challenging task, and the transducer placement is often limited only on one surface for applications such as aircraft and pipelines.

In this study, the previous reference-free NDT technique is further advanced by introducing a new PZT design named a dual PZT transducer. Using the dual PZT transducer, it is shown that reference-free damage diagnosis can be still achieved by placing 2 dual PZT transducers only on a single surface. The dual PZT is fabricated from a circular PZT by dividing the top nickel electrode layer into inner circular and outer ring portions through an etching process. Then, the presence of crack is instantly detected from the measured Lamb wave signals using the dual PZT transducers. Using dual PZT transducers, multiple Lamb wave signals can be measured in a single wave path and Lamb wave modes due to damage can be extracted from the signals. Furthermore, a new damage classifier was proposed to differentiate converted modes produced by damage from the initial errors caused by PZT imperfection.

Numerical simulations and experimental tests were conducted to validate the effectiveness of the proposed reference-free NDT technique for crack detection. Because this reference-free technique does not rely on previously obtained baseline data for crack detection, it is expected that this approach minimizes false alarms of damage due to changing operational and environmental variations experienced by in-service structures. However, the applicability of the proposed damage detection technique can be affected by sensor imperfections such as improper bonding conditions.

The sensor attachment issue will be closely investigated to reduce error in measurement. The effects of reflections, crack depth, and crack orientation on the PZT transducers on both sides of the plate have been studied in the authors' research group [23]. Similar research will be continued using proposed dual PZT transducers. Further investigation is underway to extend the proposed concept to detection of other types of damage such as delamination and corrosion.

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