

»oAA- °ø£ ,ðÇüA» AĪĵeÇÑ ÇÑ±¹ AÖ¼Ä¼ÄAaÀÇ ÇÖ,®Au °ÅÇ°±Ö,ð ĀBÁ±

μμ¼ÖÈñ; ±±èμĵ¼®; ±±èÄĪĀØ; ±ÄĪÈ, °æ

ÇÑ±¹ úÇD±ā¼μĵø Ä×Ä®³è°æĵμ'èÇDĵø
¼ĵĵ¼Ä μĵ'è¹®±, Ā».®.®μĵ 207-43

Abstract

ÇöÀç±ĪÄö ÇàÇÖÄö AÖ¼Ä¼ÄAa °ÅÇ°ĵĵi °üÇÑ ĵĵ±,μéÄ°
AÖ°ĵĵi Çü¼ÇĪĀ ±Ü»ĵĵÄĪĀ.Ī¼ Çö±Y¹è'ç,ĵĵĀ» °ĵĵi
·ACĪ°ĵĵi AÖ'Ü. ±×.³ā Çö±Y¹è'çÄ° °æĵμĀÜĵĵi ACCÖ Äĵ
Ä±°ĵĵi ÉÇĪ¹Ç.Ī AöÄ±ÇÑ ±ā¾°ĵĵiĵĵi, ³āÄ, ³»Ā ¼ÄÈÈ.Ī
°ĵĵi ±ā ¾·Æ'Ü. μĵ¼ö¼» °» ĵĵ±,ĵĵi¼ĵĵi Ā ±ā¾°ĵĵiĵĵi, ĵ
Ä±È®È± ¼YĵμÇĪ±ā ASCĪĵĵi ±ā¾°AC ÄÜ»»óĵĵi, ³āÄ, ³āĀ
ÄÜ±Y°-μĵĵĀ» °ĵĵi·ACÑ '¼öÇö±Y¹è'ç'Ā» μμÄÖÇÑ'Ü. »oAA-
°ø£ ,ðÇü'ú Ä®, ÇÈĀĪ,μ ĀBÁ±¹yĀ» AĪĵeÇĪĵĵi
KOSPI ¼ÄÄÄ ÄÜ·áĵĵi 'èÇÖ ¼ÇÄö°D¼®ÇÑ °á'ú, Çö±Y¹è
'ç,ĵĵi °ĵĵi·ACÖ '¼öÇö±Y¹è'ç'Ā» °ĵĵi·ACBÄ» '¼S ĀBÁ±
μÈ °ÅÇ°ÄĪ Äĵĵi 'Ü,¼ ¾çö»oÄ» °ĵĵi'Ü. ÆÈ± ÇÑ±¹AC
±YÄ¼AS±ā¼ÄÄĵĵĀ» °ĵĵi·ACĪĵĵi °¼¼ '¼S ¼öÇö±Y¹è'ç'Ā» AĪ
ĵĵeÇÑ °ĪÄĪ ¼ÇĪ; Çö»ó'ú ö AB °ĪÇÖÇĪĀ °ĪÄ,Ī ³ā
Ä, ³μ'Ü. ÄĪĀ AÖ¼Ä¼ÄAaÀÇ °ÅÇ°Ā» ĵĵ±,ÇĪĀμY AÖ¾
Çö±Y¹è'ç'ú ÄÜ±Y°-μĵĵĀ» ÇÖ²² °ĵĵi·ACĪĀ °ĪÄĪ ö Ä±
È®ÇÑ ĀBÁ±¹á'ú,ĵĵi ¾öÄ» ¼ö AÖÄ¼Ä» ¼Ä»çÇÑ'Ü.

1. ¼·D

°æÄĪ»ç,ĵĵi AĪ¾±āÇĪĀμY AÖ¾¼¼ °ÅÇ°Çö»oÄ° ÄĪ
ĵĵÜÇÖ ¼ö ¾·Ä Ä« °Ī°DÄ» Ä±ÄöÇĪĵĵi, ±× ÆÄÄÄ ĵĵ¼Ä
'èÇĪĵĵi 70³ā'è ÈÄ¹Y°ĪÄĪ 'Ī° »çĪ±μéÄÇ °ü¼ÆÄÇ
'è»oÄĪ μÇ°ĵĵi AÖ'Ü. Äç'« ,ðÇüĵĵi¼ĵĵi ÄĪ¹YÄüÄ.Ī ±×
±Ü°ÉÄĪ μÇ°ĵĵi AÖ'Ä ÇÖ,®Au ±ā'è,ðÇüÄ° ±ā'è¼öÄĪ·üÄĪ
°ĪÄ±μÇ¾ AÖÄ,ç ÄöÄÜÄÜμéÄĪ ASCÈÄ» È,ÇÇÇĪÄö ¾ÈÄ¼
Ä» °ĵĵi·ACĪ°ĵĵi AÖ'Ü. ±×.³ā ¼ÇĪ; μYÄĪÄĪμéÄ° ÄĪ ð
Çü'ú °ĪÇÖÇĪÄö ,øÇĪ°ĵĵi, ±Ü»» ĵĵ¼ö·Ī°ĪÄĪ ±āÄĪÇÑ °Ī
Ä,Ī °ĵĵi±āĵĵiĀ ±× °-μĵ¼ÄĪ ³È¹« Ä®±ā '¼S¹®ĵĵi ±×
°üμμÇÑ °-μĵ¼Ä» °ÅÇ°Çö»oÄ,Ī ¼³,ĵĵiÇĪ°ĵĵiÄÜ ÇĪĀ ĵĵi
±,°ĵĵi ¼ÄÄÜμÈ °ĪÄĪ'Ü.

ÄĪ¹YÄüÄ,Ī ÄÖ°ĵĵiÄÇ °ÅÇ°Ä° AÖ¼Ä¼ÄAaĵĵi¼ »y¼
μÇĀ °ÅÇ°ÄĪ'Ü. ÄĪ°ĪÄ° AÖ¼Ä¼°ĵĵiÄĪ ±Ü»» ĵĵ¼öĵĵi ÄÇ
ÇÖ °áÄ±μÇĀ °ĵĵiYĵĵi¼ ¾ö,¼³ā ±×,®μÇ¾ AÖ'Ä°ĵĵiĵĵi
ÄÇÇÖ Ä±ÄÇμÇ°ĵĵi AÖ'Ü. ±×.±μY ¼è'çÇÖÄĪ ,ðÇüÄ» ±Ü°£
Ä,Ī ÇĪĵĵi °ÅÇ°Ā» μμÄÖÇĪĀμY AÖ¾ ÇöÀç±ĪÄöÄÇ ĵĵi
±,μéÄ° Çö±Y¹è'ç,ĵĵiĀ» °ĵĵi·ACĪĵĵi'Ü. ±×.³ā Çö±Y¹è
'çÄ° °æĵμĀÜÄÇ ÄÇμĵĵi μĵ¼ö ÄĪÄ±μÈ ¼ö AÖÄ,ç ±×°Ī
Ä° ±ā¾°AC Çö±Y¹è'ç, SÄÇ ÇÑ °Ī°Dĵĵi °D°üÇĪ±ā '¼S¹®ĵĵi
Çö±Y¹è'çÄ» AĪĵeÇÖ °æĵĪ AÖ°ĵĵiÄÇ °-μĵ¼ÄĪ ¼ÇĪĀ, 'Ü
°üÄμÈ °ĵĵi ÈYÄĪ Ä,ÄÇÇÑ'Ü. μĵ¼ö¼¼ » ĵĵ±,Ā ¼è'ç
Ä» °ĵĵi·ACÖĵĵi AÖ¾¼¼ Çö±Y¹è'ç'ó ¾È¹ĵĵi ¼è'çÄÇ ¼
°YÄ» '¼ĪĀ ±ā¾°AC Äç¹«È°μĵĵi ÄÇÇÑ ÄÜ±Y°-μĵ¼éÄ»
,ðμĪ Æ·ÇÖÇĪĀ '¼öÇö±Y¹è'ç'Ā» μμÄÖÇÑ'Ü. ¼ÇÄö °D¼®
ĵĵi¼ĵĵiĀ KOSPI ¼ÄÄÄÄÄ ÄÜ·áĵĵi 'èÇĪĵĵi Wu(1997)°ĵĵi
ÄĪ¼ÄÇÑ »oAA-°ø£ ,ðÇü'ú Ä®, ÇÈĀĪ,μ ĀBÁ±¹yĀ» AĪ

ĵĵeÇĪĵĵi °ÅÇ°ÄÇ Ä®±ā,ĵĵi ĀBÁ±ÇĪĵĵi'Ü.
ÄÖ°ĵĵi °ÅÇ°ĵĵi °üÇÑ ĵĵ±,ĪĀ °üμμÇÑ °-μĵ¼Ä»
°ÅÇ°Ā,Ī °» Shiller(1981)ÄÇ °D»èÇÑ°è°ÈÄ±, S&PÄö
¼öĵĪ Dow JonesÄö¼ö,ĵĵi 'è»oÄ,Ī ¼ÇÄö°D¼®ÇÑ
West(1987)ÄÇ ĵĵ±, AÖ°ĵĵiĵĵi ¼è'çÄÇ ÄÜ±ā»ó'ú'ú
ÄS±Ü °ÈÄ±, °öÄü°D °ÈÄ±Ä» AĪĵeÇÑ Diva &
Grossman(1988)ÄÇ ĵĵ±,¼ÄÜÇÄ °È'ÜÄS±Ü °ÈÄ±
Ä» AĪĵeÇÑ Hall et al.(1999)ÄÇ ĵĵ±, ³»ÄçÄü °ÅÇ°Ā»
ÄĪ¼ÄÇÑ Froot & Obstfeld(1991)ÄÇ ĵĵ±,μĪÄĪ AÖ'Ü.
±¹³» ĵĵ±,ĪĀ °ÅÇ° ÇÄ,®¹¼öÄ» μμÄÖÇÑ ±è±Öĵĵi, Ä±
±āö(1991), ³»ÄçÄü °ÅÇ°Ā» ±¹³» ÄÜ·áĵĵi ÄüĵeÇÑ ±è
±Öĵĵi(1995), Wu(1997)ÄÇ 'æ¹yÄ» ±¹³»ÄÜ·áĵĵi ÄüĵeÇÑ
ÄĪÄ±æD(1999)ÄÇ ĵĵ±, μĪÄĪ AÖ'Ü.

2. ĵĵ±, 'æ¹y

2-1. °D¼® ,ðÇü

°» ĵĵ±,ĵĵi¼ĵĵiĀ Wu(1997)ÄÇ ,ðÇüÄ» μμÄÖÇĪĵĵi'Ü.
ÄÜ»èÄÇ ¼öÄĪ·üÄĪ r·Ī ÄĪÄ±ÇÖ °æĵĵi ÇÖ,®Au ±ā'è
,ðÇüÄ° 'ÜÄ¼ö'ú °°'Ü.

[E_t (P_{t+1} + D_t) - P_t] / P_t = r (1)

ĵĵ±ā¼ P_tĀ t¼ÄÄĪÄÇ ¼ÇÄüÄÖ°ĵĵi, D_tĀ ¼ÇÄü¹è'ç, E_tĀ
t¼ÄÄĪ±ĪÄöÄÇ Ä±°,ĵĵi Äĵ°ÇÄ,Ī ÇĪĀ ±ā'è°ÄÄ» ÄÇĪĪ
ÇĪĵĵi rÄ° ÇÈĵĵi ¼ÇĪ; ¼öÄĪ·üÄĪ'Ü. ¼Ä(1)ĵĵi¼ĵĵiĀ
Ä°μμÈ AÖ°ĵĵiÄÇ μĵÄÄ¹æÄ¼ÄÄ° Ä¼ÄÇ AÖ°ĵĵiĵĵi ÇāĵeÇĪÄö ¾ÈÄö
,, Çö¼Çĵĵi¼ĵĵiĀ AÖ°ĵĵiĀ °ü'èÄ®°ĵĵi »Ö ¾È¹ĵĵi °ü¼ö
®°ĵĵiμÇĀ °ĪÄĪ °ĵĵiÉÇĪ'Ü. μĵ¼ö¼¼ Ä¼ÄÇ AÖ°ĵĵiĵĵi
°ĵĵiÄö'ĪÄ» ÇÇÇĪ°ĵĵi Ä¼ÄÇ °ÅÇ°Ā» ÇāĵeÇĪ±ā ÄSÇÖ¼¼
Campbell&Shiller(1988)ĵĵi μĵ¼ö(1)ÄÇ ·Ī±× ¼æÇü ±Ü
»çÄĵĵi,ĵĵiÇĪĵĵi,é 'ÜÄ¼ö'ú °°'Ü.

q = k + ρ E_t p_{t+1} + (1 - ρ) d_t - p_t (2)

qĀ ÇÈĵĵi¼ÇĪ; ¼öÄĪ·üÄÇ ·Ī±×°ÄĪ°ĵĵi, ρĀ AÖ°ĵĵiĵĵi
AÖ°ĵĵi '× ¼è'ç±YÄÇ ÇÖ °ÉÄÇ Äö±Ö °ñÄ², kĀ -ln
(ρ)-(1-ρ)ln(1/ρ-1)ÄĪ,ç p_tĵĵi d_tĀ °ç°ç ¼ÇÄüÄÖ°ĵĵi
ĵĵi ¼ÇÄü¹è'çÄÇ ·Ī±×°ÄĪ'Ü. »±āÄĵĵi» ÄæÄ·μÇĀ
°æĵĵi ¼Ä(2)ĵĵi 'èÇÑ ÄĪÇÖĀĀ 'ÜÄ¼ö'ú °°'Ü.

p_t^f = (k - q) / (1 - ρ) + (1 - ρ) ∑_{t=0} ρ^t E_t (d_{t+1}) (3)

ÄĪ ¼ÄÄ° ·Ī±× AÖ°ĵĵiĵĵiĀ ·Īĵĵi ±ā'è¹è'çÄÇ ·Ī±×°ÄÄÇ Çö
°ĵĵiÇÖÄ,Ī ÄĪ·ç¾ÄüÄ» °ĪÄĪ°ĵĵi AÖ'Ü. ĵĵ±ā¼¼ ,,¾Ä,»
±āÄĵĵiÇÄĪ Ä·μÇÄö ¾ÈĀ'Ü,é ¼Ä(3)Ä° Æ¼°ÇÖ°ĵĵi μÇ
,ç ÄĪ¼S ÄĪ¹YÇÖĀĀ ¼Ä(3)ĵĵi °ÅÇ°Ç×Ä» Æ·ÇÖÇĪĀ 'ÜÄ¼ö
°ü °°Ä° ¼ÄĪ μÈ'Ü.

$$p_t = (k - q) / (1 - \rho) + (1 - \rho) \sum_{i=0}^{\infty} \rho^i E_t(d_{t+i}) + b_t = p_t^f + b_t \quad (4)$$

$$E_t(b_t) = (1/\rho)^i b_t \text{ for } i=1,2,3... \quad (5)$$

ARIMA(h,1,0) model. The error term ϵ_t is assumed to be a white noise process with mean zero and constant variance σ^2 . The parameters μ and δ are estimated using the Kalman filter algorithm.

$$\Delta p_t = (1 - \rho) \sum_{i=0}^{\infty} \rho^i [E_t(d_{t+i}) - E_{t-1}(d_{t+i+1})] + \Delta b_t = \Delta p_t^f + \Delta b_t \quad (6)$$

The Kalman filter algorithm is used to estimate the parameters of the state space model. The initial conditions are set to zero.

$$\Delta d_t = \mu + \sum_{j=1}^h \phi_j \Delta d_{t-j} + \delta_t \quad (7)$$

The state vector Y_t is defined as $Y_t = (U + A Y_{t-1} + v_t)$, where U is the drift vector, A is the transition matrix, and v_t is the disturbance vector. The initial conditions are $Y_0 = (0, 0, 0, 0, 0)$.

The Kalman filter algorithm is used to estimate the parameters of the state space model.

$$Y_t = (\Delta d_t, \Delta d_{t-1}, \dots, \Delta d_{t-h+1})'$$

$$U = (\mu, 0, \dots, 0)$$

$$v_t = (\delta_t, 0, 0, \dots, 0)'$$

$$A = \begin{bmatrix} \phi_1 & \phi_2 & \phi_3 & \dots & \phi_{h-1} & \phi_h \\ 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & 1 & 0 \end{bmatrix} \text{ h j h C a - A}$$

The Kalman filter algorithm is used to estimate the parameters of the state space model.

$$\Delta p_t = \Delta d_t + M \Delta Y_t + \Delta b_t \quad (9)$$

The Kalman filter algorithm is used to estimate the parameters of the state space model.

$$b_t = (1/\rho) b_{t-1} + \eta_t \quad (10)$$

The Kalman filter algorithm is used to estimate the parameters of the state space model.

The Kalman filter algorithm is used to estimate the parameters of the state space model.

The Kalman filter algorithm is used to estimate the parameters of the state space model.

2-2. ARIMA model

The ARIMA model is used to estimate the parameters of the state space model.

3. Kalman filter

3-1. Model

The Kalman filter algorithm is used to estimate the parameters of the state space model.

		$\epsilon_t = \sigma \epsilon_t$ $\epsilon_t \sim N(0, \sigma^2)$
AÚ. á	$\epsilon_t = \sigma \epsilon_t$ $\epsilon_t \sim N(0, \sigma^2)$	$\epsilon_t = \sigma \epsilon_t$ $\epsilon_t \sim N(0, \sigma^2)$
	$\epsilon_t = \sigma \epsilon_t$ $\epsilon_t \sim N(0, \sigma^2)$	$\epsilon_t = \sigma \epsilon_t$ $\epsilon_t \sim N(0, \sigma^2)$
±á°f	$\epsilon_t = \sigma \epsilon_t$ $\epsilon_t \sim N(0, \sigma^2)$	$\epsilon_t = \sigma \epsilon_t$ $\epsilon_t \sim N(0, \sigma^2)$

Table 1: Kalman filter parameters

The Kalman filter algorithm is used to estimate the parameters of the state space model.

3-2. ARIMA model

The ARIMA model is used to estimate the parameters of the state space model.

1/2A;μeA» ±āA0A, .I A°o0 °-Cī°i AÖ.U. ±x. -CÑ A«
 °-E-°i Aİ³±³- 1/2A;A° 1/2Cö±Y¹è´çAİ ±P°YÈ± °1/2DÇÑ
 1/2A;°ü AİÄ;Cİ´ç´.U. A1/2AÇ °AÇ°Aİ AÜ»e°i°YA» °ü1/2
 A°;Cİ°i AÖ´A °IA, .I Ç01/2C0 1/2 AÖ´U, é 1/2Cö±Y¹è
 ´çA» Aİ,çCÑ °æ;ì´A 89³a°IAÍ 94³a EÄ¹Y±ā±IAö AÖ
 °i°i ç0°i °iÄ;AÇ 3/4 2/3A±μ. I °ü1/2A°; μÇ°i AÖ
 3/4ü´U°i Ç0 1/2 AÖ´U. 80³a´è EÄ¹Y±āAÇ °æ;ì çì, ³a
 ¶°°i ±0μAÇ È°E²±āç´´U°i °EÄ0μÇ³/4 ç0°i AÖ°i Aö1/2
 μμ 1000A» ³N³/4´A ÇāAA, ! °, ç´Aö, , Aİ´A AÖ³/4Aö
 ¹è´ç±YÄ» °i. AÇ0 °»´U, é 1/2A; AN³/4Aİ ´ó ³0³/0³/4 3/4
 ÇÖA» AÇ¹IÇI´ç, Aİ´IA° AÖ°i Aö1/2°i 1000A» ³N´0¶°
 μμ ±x°IA° 1/2Cö±Y¹è´çA» °i. AÇBA» ¶S ±x °iÄ;°i °ü
 1/2A°; μE °IAI³/4ü´U°i Ç01/2C0 1/2 AÖ´U. 95³a°IAÍ 98
 ³a , »±IÄöμμ , ¶Aü; AöAİ´U. AÈ± ±YÄ¶AS±ā 1/2A; ç;´
 ´A AÖ°;°i ç0°i°iÄ;AÇ 1/2A±μ. I A°; μÇ³/4 °iÄā ³.
 A° °AÇ°A» °, Aİ°i AÖ°i 99³a AÈ¹YÄIÈÄ 99³a , »±IÄö
 AÖ°; Aö1/2°i ´U1/2 1000A» ³N³/4´A, é1/4 °AÇ°A° ´U1/2
 3/4AÇ °A, .I ±P°YÈ± Ä;1/4°i AÖ´U. Aİ´IA° 1/2A; AN³/4
 A° ±P°YÈ± 1/2A; AÇN¶Y ¹YÇ0 1/2Cö±Y¹è´çA° çÄÈ±. A 1/2
 Cİ°0 °1/2DÇI´ç, A; çì ±PCÑ Aö´´CüAA, ! °, Aİ´A °IA,
 .I ±x ç0AIA» 1/2, íC0 1/2 AÖ´U. Aİ´CÑ A±Aİ´I ¹I´ç
 3/4 °, 3/4E Çö±Y¹è´ç, A» Aİ,çCÑ °æ;ì´A °D1/2° °á°ü°i
 1/2A; ±YÄ¶AS±ā ´ç1/2AÇ »0E²°ü °A, °; AÖ³/4 °, Aİ´ç
 1/2A; Çö»óA» AB 1/2, íCİAö , 0Cİ´A °IA, .I ³aA, ³a, ç
 μü¶°1/4 Çö±Y¹è´ç Aİ,çÜAÇ AÜ±Y°-μçμeA» °i. AÇI´A °I
 Aİ °AÇ°AÇ ABÁ±ç; AÖ³/4 ´óç;í A±E°1/2A» ±āÇ0 1/2 AÖ
 A1/2A» 1/2A»çCÑ´U.

4. °á·D

AÜ»e °i°YAC Çö°i, ðÇüA° °ð 1Ì. j ¹è´çÈä, SÄÇ
 ÇöAÇ°; Ä;AÇ ANÇÖAİ ÇöAÇAÇ °i°YAOA» AÇ¹IÇI´ç, »±ā
 A¶°ÇAİ AæA·μÇAö 3/4E³/4E/4 1/2A; °i°YAI Aİ °iÄ; ! 1p
 3/4³a´A ±«, °; »ý±ā´A Çö»óA» °AÇ°A, .I °, 3/4´U. ±x
 ·±μY Ç0°i, ðÇüA» Aİ´ç´A ±U°» çä1/2Aİ ¹è´çA» °i. A
 Ç0ç; AÖ³/4 1/4 Çö±Y¹è´ç, A» »ý°çCİ´A °IAI ±x A, ´ç
 1/2ç; AÖ³/4 1°A;°; A;±āμÇ³/4i°i, °» ç´±, AÇ 1/2Aö°D1/2
 A» AèCİ´ç° °ü. A ç´±, μeAÇ ÇÈçä1/2Aİ A; 1/2AμÇ³/4ü´U.

3/4ÖA, .I´A Aİ´CÑ »ð. I ç;í CüAAÄÇ ¹è´çA» °AÇ° , ð
 Çüç;1/4 °i. AÇI±ā AÇCÑ ¹æ¹·D°ü , ðÇüAÇ 1/2A; ç;í °ü
 CÑ ç´±, °; ÇÈçäÇ0 °IA, .I »ý°çμÇ, AÜ´á È°° Aö, é
 ç;í 1/4 ´óç;í çäAİCÑ °30° ±ā³/4 1x °30° »è³/4ç;í È°çè
 Ç0 1/2 AÖ´A ¹æ¹EÄ» , ð»óCİ´A °Iμμ ÇÈçäCİ´U°i °»
 ´U.

<Äü°i¹@Ça>

±è±0çμ, A±āçö, ÇÖ, °Äü °AÇ°ç;í °üCÑ ç´±, CÑ±¹ AÖ
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±è±0çμ, ³»AçÄü °AÇ°ç;í °üCÑ ç´±, CÑ±¹ AÖ1/21/2AAä
 ç;í 1/2AÇ 1/2Aö °D1/2, AÇ¹«ç´±, 1995, A;1E£,
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